



# HyperLasso: Bounded Model Checking of $\forall^+ \exists^+$ -Liveness Hyperproperties

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HYPER 2026 (adapted from CAV 2026)

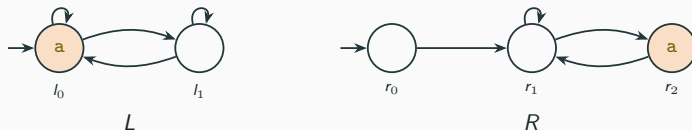
# Hyperproperties: relating multiple executions

Some properties relate **multiple** traces: non-interference, robustness, synthesis, ...

**HyperLTL** = LTL + explicit quantification over traces:

$$\varphi ::= \forall \pi \cdot \varphi \mid \exists \pi \cdot \varphi \mid \psi \qquad \psi ::= \mathbf{a}_\pi \mid \neg \psi \mid \psi \wedge \psi \mid \mathbf{X} \psi \mid \psi \mathbf{U} \psi$$

**Running example** (quantifiers may range over *different* models):



$$\forall \pi_1 : L \cdot \exists \pi_2 : R \cdot \mathbf{F}(\mathbf{a}_{\pi_1} \wedge \mathbf{a}_{\pi_2}) \quad \text{“some counterpart eventually sees } \mathbf{a} \text{ simultaneously”}$$

Refute by finding a witness of the dual  $\exists \pi_1 : L \cdot \forall \pi_2 : R \cdot \mathbf{G}(\neg \mathbf{a}_{\pi_1} \vee \neg \mathbf{a}_{\pi_2})$

**✗ false:**  $l_0(l_1)^\omega$  sees **a** only at step 0, but traces of  $R$  need  $\geq 2$  steps to reach **a**.

# Bounded model checking

A model is a Kripke structure  $K = \langle S, S_0, \delta, L \rangle$ . BMC is **symbolic**: the initial-state predicate  $S_0$  and transition predicate  $\delta$  are over Boolean state vectors.

**Bug finding by unrolling:** search for a length- $k$  path of  $K$  that violates  $\varphi$

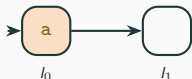
$$\underbrace{\llbracket K \rrbracket_k}_{\text{model}} \wedge \underbrace{{}_0\llbracket \neg\varphi \rrbracket_k}_{\text{property}} \rightsquigarrow \text{SAT}$$

## Theorem (infinite inference for LTL)

$\not\models_k \varphi \Rightarrow \not\models \varphi$  every bounded counter-example is a **real bug** of  $K$

A bounded path can **refute** a property over all traces:

**✗ safety**  $\exists \pi : L \cdot \mathbf{F} \neg \mathbf{a}_\pi$  has a **witness**



a finite **prefix**  $l_0 l_1$  of  $L$  reaches  $\neg \mathbf{a}$

**✗ liveness**  $\exists \pi : R \cdot \mathbf{G} \neg \mathbf{a}_\pi$  has a **witness**



an infinite **lasso**  $r_0(r_1)^\omega$  of  $R$  never reaches **a**

Trace quantifiers  $\Rightarrow$  one copy of the symbolic unrolling per trace  $\rightsquigarrow$  QBF

HYPERQB keeps **finite-prefix** semantics (**no loops**)  $\Rightarrow$  conclusive only for some  $\forall\exists$ -liveness

Consider refuting the dual properties:

### Valid properties, any models

$$\text{Orig} : \forall \pi_1 : L \cdot \exists \pi_2 : R \cdot \mathbf{F}(a_{\pi_1} \vee a_{\pi_2})$$

$$\text{Dual} : \exists \pi_1 : L \cdot \forall \pi_2 : R \cdot \mathbf{G} \neg(a_{\pi_1} \vee a_{\pi_2})$$

✓ **no witness** for any  $k$ : **a** in first state  $l_0$ .

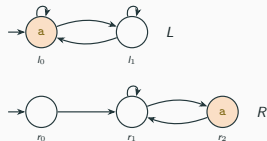
### Invalid properties, terminating models

$$\text{Orig} : \forall \pi_1 : L^\downarrow \cdot \exists \pi_2 : R^\downarrow \cdot \mathbf{F}(a_{\pi_1} \wedge a_{\pi_2})$$

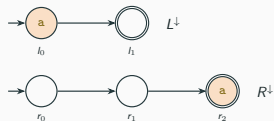
$$\text{Dual} : \exists \pi_1 : L^\downarrow \cdot \forall \pi_2 : R^\downarrow \cdot \mathbf{G} \neg(a_{\pi_1} \wedge a_{\pi_2})$$

✗ **witness** for  $k = 2$ : traces eventually halt without **a** at  $l_1$ .

under *pessimistic* semantics



under *optimistic halting* semantics



For HyperLTL, refuting **liveness** still needs infinite **lasso** counter-examples.

*“[...] the model under  $\forall$  would have to be explored to the maximal lasso length [...], which is **doubly-exponential**. Therefore, this naive approach would be highly inefficient.”*

HYPERQB 2.0 instead recovers loops via **simulation** between the states of the two models.

$$\exists \pi_1 : L \cdot \forall \pi_2 : R \cdot \mathbf{G} \neg (\mathbf{a}_{\pi_1} \wedge \mathbf{a}_{\pi_2})$$

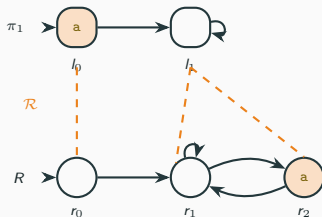
Our running example falls into their **EA-simulation** fragment.

Guess a **lasso**  $\pi_1$  of  $L$  and a relation  $\mathcal{R} \subseteq S_L \times S_R$ :

- $(\pi_1(0), r_0) \in \mathcal{R}$  for **every** initial state  $r_0$  of  $R$ .
- closed under **every** successor of  $R$  (wrapping at  $t$ 's loop)
- $\neg (\mathbf{a}_{\pi_1} \wedge \mathbf{a}_{\pi_2})$  on every pair of  $\mathcal{R}$

✓ **true** with  $\pi_1 = l_0(l_1)^\omega$  and  $\mathcal{R} = \{(l_0, r_0), (l_1, r_1), (l_1, r_2)\}$ .

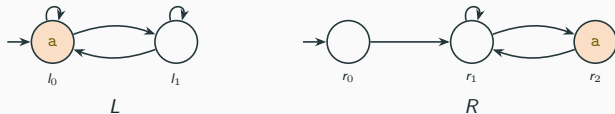
**Limitations:**  $R$  is unrolled over its **explicit** state space, only for  $\mathbf{G}$ .



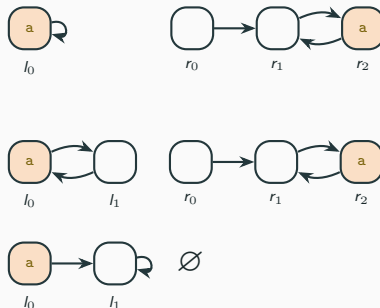
# Our problem: BMC for HyperLTL, in general

Find a  $k$ -loop witness of  $\exists \pi_1 \cdot \forall \pi_2 \cdot \mathbf{G}(\neg a_{\pi_1} \vee \neg a_{\pi_2})$ .

But the inner  $\forall$  now ranges only over  $k$ -bounded counterparts, an **under-approximation**:

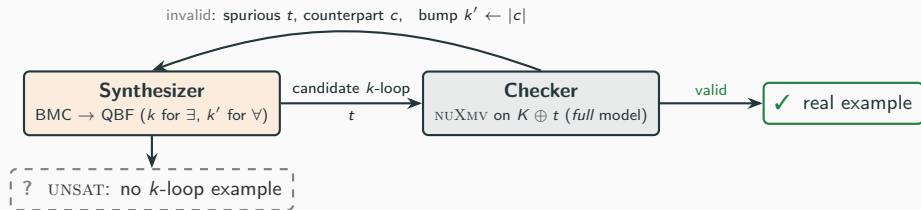


- $k = 0$ :  $\pi_1 = (l_0)^\omega$ ;  $R$  has *no* 0-loops
  - $\forall \pi_2$  holds vacuously  $\Rightarrow$  **bug**?
  - ✓ **spurious**:  $\mathbf{G}(\neg a_{\pi_1} \vee \neg a_{\pi_2})$  does not hold for the  $(2, 1)$ -loop  $r_0(r_1 r_2)^\omega$  (it needs  $k = 2$ )
- $k = 1$ :  $\pi_1 = (l_0 l_1)^\omega$ 
  - ✓ spurious again: same counterpart (both see **a** at step 2)
- $k = 1$ :  $\pi_1 = l_0(l_1)^\omega$ 
  - ✓ a **true bug**: **a** only at step 0, unmatched by any trace from  $R$



# Our approach: synthesize, then check

**Key observation:** with a *single* quantifier alternation  $\exists^+ \forall^+ \neg \psi$ , once the  $\exists$ -traces are fixed, what remains is  $\forall^+ \neg \psi \Rightarrow$  checkable by a **complete** LTL model checker via a product construction.



CEGAR-flavoured loop; on the example:

1. synthesizer ( $k=1, k'=1$ ) proposes  $(l_0 l_1)^\omega \Rightarrow$  checker deems **invalid**, counterpart  $r_0(r_1 r_2)^\omega$
2. synthesizer ( $k=1, k'=2$ ) proposes  $l_0(l_1)^\omega \Rightarrow$  checker deems **valid**

# Our approach: guarantees

## Theorem (infinite inference)

Every  $k$ -loop returned by the procedure witnesses both  $\models_k \exists^+ \forall^+ \neg \psi$  *and*  $\models \exists^+ \forall^+ \neg \psi$ .

**Why** a returned lasso unrolls to any  $k' > k$ , and longer universal counterparts were already discharged (the checker is complete).

**Takeaway** BMC's value proposition is **restored** (every reported counter-example is **real**)

**Note** Lasso-shaped traces capture all relevant infinite paths for HyperLTL.

## Lemma (bounded inference)

If no witness is returned, then  $\not\models_k \exists^+ \forall^+ \neg \psi$ .

**Why** growing the inner bound  $k' \geq k$  only *adds* universal counterparts, so discarded candidates stay discarded.

**Takeaway** Monotonic confidence as  $k$  grows (bounded completeness *for bound*  $k$ ).

**Note** Identifying a completeness threshold remains orthogonal and generally infeasible.

# The synthesizer: reduction to QBF

General schema =  $k$  copies of each model's state variables + a loopback index per trace:

$$\llbracket \exists \pi_{1\dots n} \dots \forall \pi_{n+1\dots m} \cdot \psi \rrbracket_k := \exists \overline{x_{\pi_{1\dots n}}} \cdot \exists l_{1\dots n} \dots \forall \overline{x_{\pi_{n+1\dots m}}} \cdot \forall l_{n+1\dots m} \cdot$$

$$\underbrace{\bigvee_{0 \leq i_1, \dots, i_m \leq k}}_{\text{loop selection}} \left( \underbrace{\bigwedge_{1 \leq j \leq m} l_j = i_j}_{\exists \text{ models}} \wedge \underbrace{\bigwedge_{1 \leq j \leq n} \llbracket \pi_j \rrbracket_k^{i_j}}_{\forall \text{ models}} \wedge \left( \underbrace{\bigwedge_{n < j \leq m} \llbracket \pi_j \rrbracket_k^{i_j}}_{\text{property}} \rightarrow 0 \llbracket \psi \rrbracket_k^{\{\pi_1 \mapsto i_1, \dots, \pi_m \mapsto i_m\}} \right) \right)$$

The whole encoding for the example at  $k = 1$ :

$$\exists x_L^0 x_L^1 \cdot \exists l_1 \cdot \forall x_R^0 x_R^1 \cdot \forall l_2 \cdot$$

$$\bigvee_{i_1, i_2 \in \{0,1\}} \left( l_1 = i_1 \wedge l_2 = i_2 \wedge \llbracket \pi_1 \rrbracket_1^{i_1} \wedge \left( \llbracket \pi_2 \rrbracket_1^{i_2} \rightarrow 0 \llbracket \mathbf{G}(\neg \mathbf{a}_{\pi_1} \vee \neg \mathbf{a}_{\pi_2}) \rrbracket_1^{\{\pi_1 \mapsto i_1, \pi_2 \mapsto i_2\}} \right) \right)$$

where the models unroll and **close a loop** back to state  $i$ , e.g.

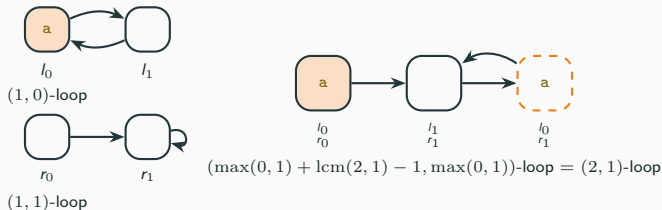
$$\llbracket \pi_1 \rrbracket_1^0 = l_L(x_L^0) \wedge R_L(x_L^0, x_L^1) \wedge \mathbf{R}_L(x_L^1, x_L^0)$$

and the body expands over the *combined* lasso, e.g. for  $(i_1, i_2) = (0, 1)$ :

$$(\neg \mathbf{a}_L^0 \vee \neg \mathbf{a}_R^0) \wedge (\neg \mathbf{a}_L^1 \vee \neg \mathbf{a}_R^1) \wedge \underbrace{(\neg \mathbf{a}_L^0 \vee \neg \mathbf{a}_R^1)}_{\text{indices from different periods}}$$

# The synthesizer: aligning lassos of different periods

Evaluating  $\psi$  over a *pair* of lassos = walking both loops synchronously (up to  $k^m$  for  $m$  traces):  
 a combined lasso with loopback  $\underline{l} = \max(i, j)$  and last index  $\underline{k} = \underline{l} + \text{lcm}(\text{periods}) - 1$



**Key insight: do not create state variables beyond  $k$**

States of the combined path beyond  $k$  are **virtual** (dashed): the formula indexes back into the depth- $k$  variables by modular arithmetic over each loop's period,

$$i[\![a_\pi]\!]_k^\Lambda := \begin{cases} a_\pi^i & i < \Lambda(\pi) \\ a_\pi^{\underline{i}} & \text{otherwise} \end{cases} \quad \underline{i} := \Lambda(\pi) + ((i - \Lambda(\pi)) \bmod (k + 1 - \Lambda(\pi)))$$

with temporal operators unfolding up to  $\underline{k}$ , and  $\mathbf{X}$  wrapping back to  $\underline{l}$ .

# The checker: an off-the-shelf LTL model checker

Candidate = concrete lassos  $t_1, \dots, t_n$  for the  $\exists$ -traces.

Verify  $\forall \pi_1 \dots \forall \pi_m \cdot \psi$  where:

- $\exists$ -models are pinned to their candidate
  - $K_{\pi_i} \oplus t_i$  adds an index variable + invariants forcing the single trace  $t_i$
- all models **composed** into one; negated body as the LTLSPEC
- solved by NUXMV (*complete*, no bound)

A counter-example  $c \Rightarrow$  candidate invalid

- $|c|$  is then used as the new inner bound  $k'$

Checking candidate  $(l_0 l_1)^\omega$ :

```
MODULE main
VAR L_l : 0..1;  R_r : 0..2;
    L_s : 0..1;  -- lasso index
ASSIGN
  init(L_l) := 0; ...
  init(R_r) := 0; ...
  init(L_s) := 0;
  next(L_s) := case L_s < 1 : L_s+1;
                TRUE : 0; esac;
INVAR -- pin L to the candidate
  (L_s = 0 & L_l = 0) |
  (L_s = 1 & L_l = 1);
DEFINE L_a := (L_l = 0);
        R_a := (R_r = 2);
LTLSPEC G (!L_a | !R_a)
```

# A benchmark for liveness hyperproperties

Existing suites contain mostly safety properties or toy examples  $\Rightarrow$  new public benchmark: liveness hyperproperties with a single alternation, over non-terminating models of parametric size.

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## Verification ( $\forall^+ \exists^+$ with liveness)

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|          |                                                                                 |
|----------|---------------------------------------------------------------------------------|
| gni      | generalized non-interference in a conference system (decisions eventually made) |
| rc/ser   | DB isolation-level equivalence, Read Committed vs Serializability               |
| cni      | non-interference in a multi-threaded PIN-masking program, fair scheduler        |
| selfstab | Herman's self-stabilization on a ring (eventually a single token)               |
| robust   | robustness of Lamport's Bakery (a halted process cannot starve the others)      |

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## Synthesis ( $\exists^+ \forall^+$ with safety)

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|      |                                                                          |
|------|--------------------------------------------------------------------------|
| spec | semaphore controller synthesis (Mealy machine as frozen variables)       |
| plan | robot path planning avoiding $e$ moving enemies on an $n \times n$ board |

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# Results

Setup: AUTOHYPER (explicit-state, complete tool for any model/property) with its best automata backend per problem, witness mode; 300s timeout; MacBook Pro M1.

|               | Result | Magnitude             | AutoHyper                                                                         | HyperLasso |
|---------------|--------|-----------------------|-----------------------------------------------------------------------------------|------------|
| gni_any_3x3   | ✗      | $(10^9)^3$            |  | 3.8        |
| rc_ser_3x2    | ✗      | $10^6 \times 10^6$    |  | 0.4        |
| cni_any_2     | ✗      | $(10^3)^2$            |  | 65.5       |
| selfstab_gf_7 | ✗      | $(10^3)^2$            |  | 0.7        |
| robust_crit_3 | ✗      | $(10^3)^2$            |  | 8.7        |
| spec2_4x4     | ✓      | $10^{14} \times 10^3$ |  | 2.6        |
| plan_4x3      | ✓      | $(10^2)^4$            |  | 1.7        |
| selfstab_lf_3 | ✓      | $(10^1)^2$            | 0.8                                                                               | 117.8?     |

**RQ1 — versus AutoHyper** HYPERLASSO wins consistently beyond minimal scopes.

AUTOHYPER wins selfstab\_lf\_3.

AUTOHYPER times out out from  $\sim 10^5$  states (e.g. selfstab\_lf\_5).

**RQ2 — are spurious candidates real?**

Yes, in 6 of 7 problem families; but  $\leq 2$  iterations ever needed, checker time negligible, one  $k'$  jump usually suffices.

? **Incomplete** results: valid answers are only “valid up to  $k$ ”, and a small  $k$  can render some problems vacuous (e.g. fairness in selfstab needs the token to circle the ring once).

# Takeaways

1. **Bounded refutation is unsound for  $\forall\exists$ -liveness**: over reactive models, bounded counter-examples can be spurious.
2. **Synthesize, then check**: a QBF lasso-synthesizer + a complete LTL checker (self-composition, one alternation) restore infinite inference.
3. **Symbolic scales**: HYPERLASSO consistently outperforms the explicit-state AUTOHYPER on models beyond  $\sim 10^5$  states.

**Future work**: arbitrary quantifier alternations; completeness results beyond bug-finding; a proper CEGAR loop.



<https://github.com/haslab/HyperLasso>



<https://doi.org/10.5281/zenodo.19850821>

Thank you!